

EE3414

Multimedia Communication Systems - I

Sampling and Interpolation

Yao Wang

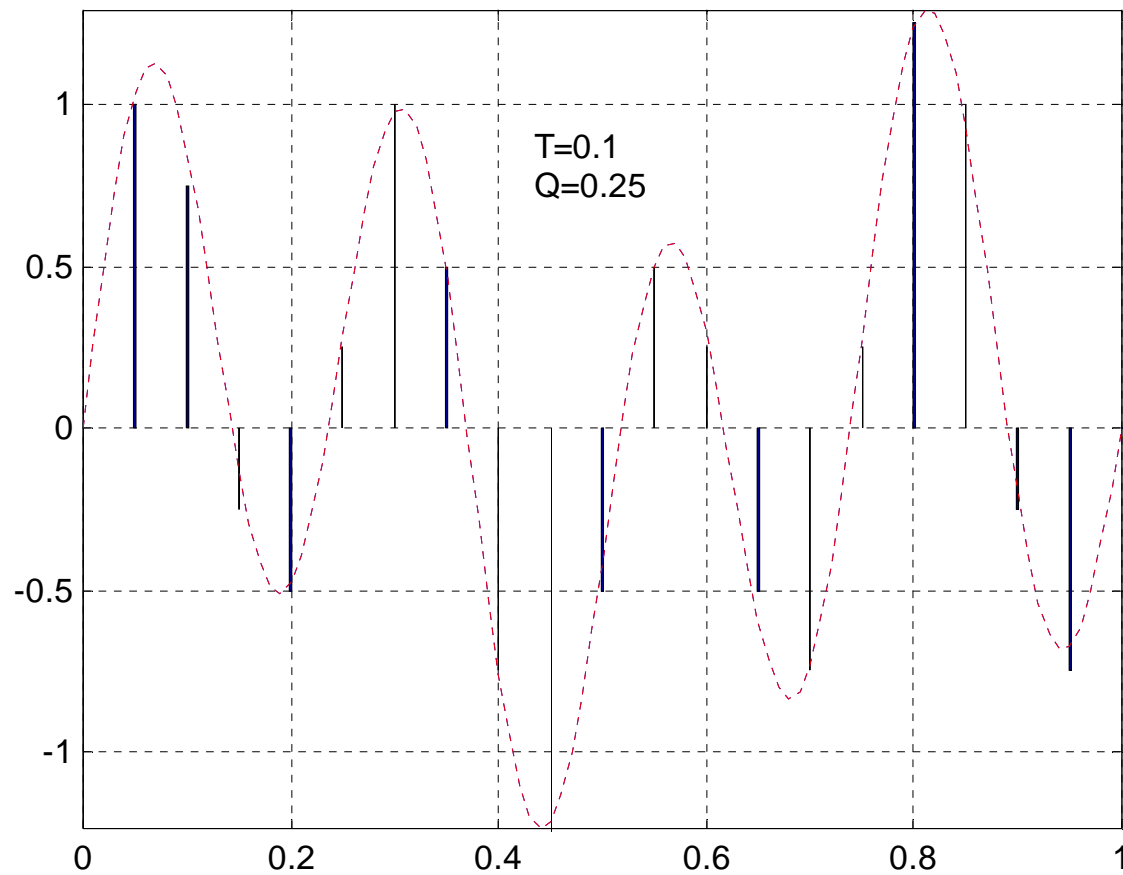
Polytechnic University, Brooklyn, NY11201

<http://eeweb.poly.edu/~yao>

Outline

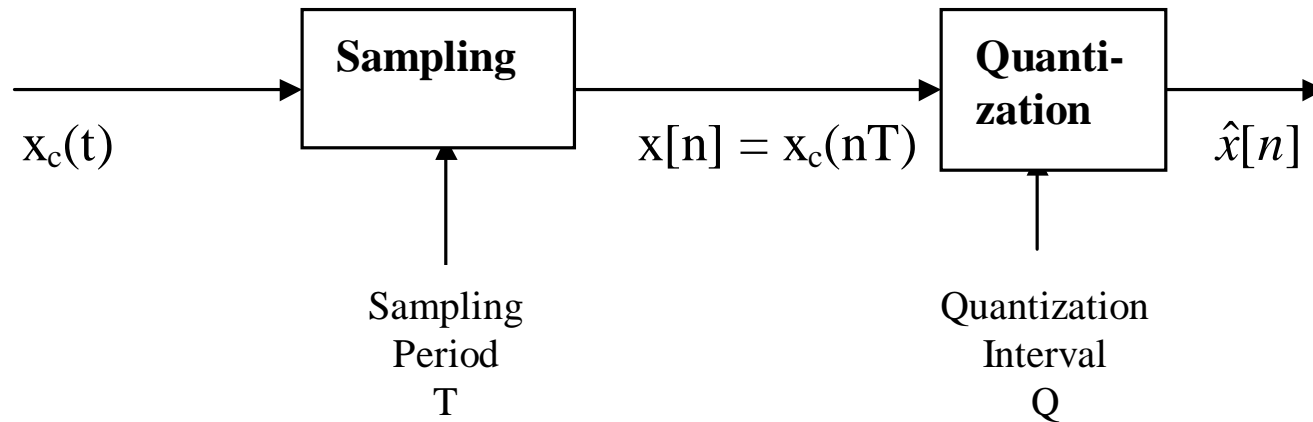
- Basics of sampling and quantization
 - A/D and D/A converters
- Sampling
 - Nyquist sampling theorem
 - Aliasing due to undersampling:
 - temporal and frequency domain interpretation
 - Sampling sinusoid signals
- Reconstruction from samples
 - Reconstruction using sample-and-hold and linear interpolation
 - Frequency domain interpretation (sinc pulse as interpolation kernel)
- Sampling rate conversion
 - Down sampling
 - Up sampling
 - Demonstration

Analog to Digital Conversion



A2D_plot.m

Two Processes in A/D Conversion



- Sampling: take samples at time nT
 - T : sampling period;
 - $f_s = 1/T$: sampling frequency
$$x[n] = x(nT), -\infty < n < \infty$$
- Quantization: map amplitude values into a set of discrete values $\pm pQ$
 - Q : quantization interval or stepsize
$$\hat{x}[n] = Q[x(nT)]$$

How to determine T and Q?

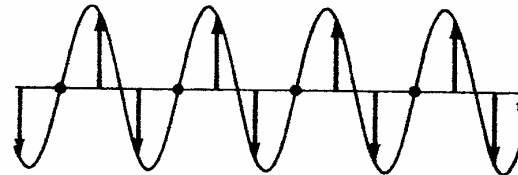
- T (or f_s) depends on the signal frequency range
 - A fast varying signal should be sampled more frequently!
 - Theoretically governed by the Nyquist sampling theorem
 - $f_s > 2 f_m$ (f_m is the maximum signal frequency)
 - For speech: $f_s \geq 8 \text{ KHz}$; For music: $f_s \geq 44 \text{ KHz}$;
- Q depends on the dynamic range of the signal amplitude and perceptual sensitivity
 - Q and the signal range D determine bits/sample R
 - $2^R = D/Q$
 - For speech: $R = 8 \text{ bits}$; For music: $R = 16 \text{ bits}$;
- One can trade off T (or f_s) and Q (or R)
 - lower $R \rightarrow$ higher f_s ; higher $R \rightarrow$ lower f_s
- We consider sampling in this lecture, quantization in the next lecture

Nyquist Sampling Theorem

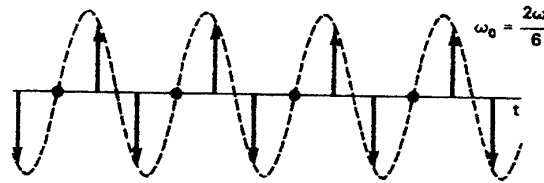
- Theorem:
 - If $x_c(t)$ is bandlimited, with maximum frequency f_m (or $\omega_m = 2\pi f_m$)
 - and if $f_s = 1/T > 2 f_m$ or $\omega_s = 2\pi/T > 2 \omega_m$
 - Then $x_c(t)$ can be reconstructed perfectly from $x[n] = x_c(nT)$ by using an ideal low-pass filter, with cut-off frequency at $f_s/2$
 - $f_{s0} = 2 f_m$ is called the *Nyquist Sampling Rate*
- Physical interpretation:
 - **Must have at least two samples within each cycle!**

Temporal Domain Interpretation: Sampling of Sinusoid Signals

Sampling above
Nyquist rate
 $\omega_s = 3\omega_m > \omega_{s0}$

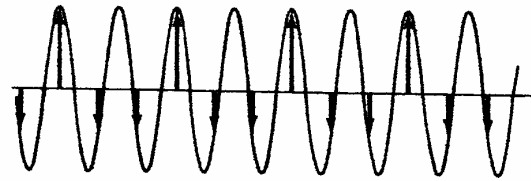


Reconstructed
= original

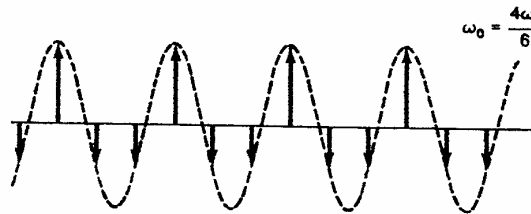


(b)

Sampling under
Nyquist rate
 $\omega_s = 1.5\omega_m < \omega_{s0}$



Reconstructed
≠ original

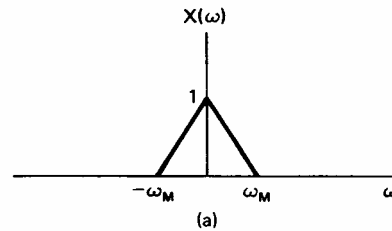


(c)

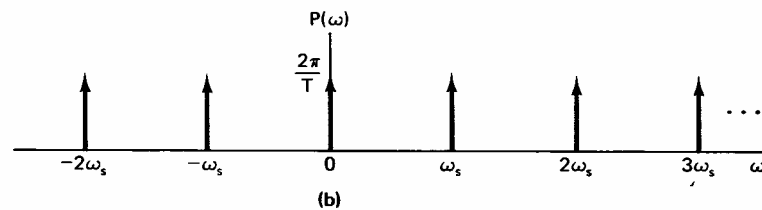
Aliasing: The reconstructed sinusoid has a lower frequency than the original!

Frequency Domain Interpretation of Sampling

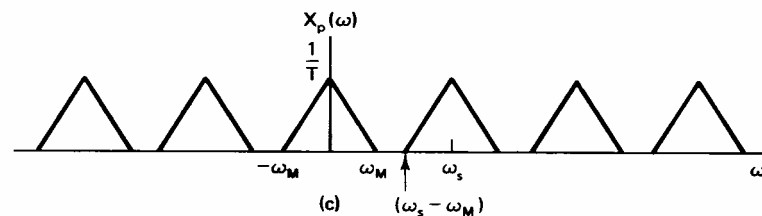
Original signal



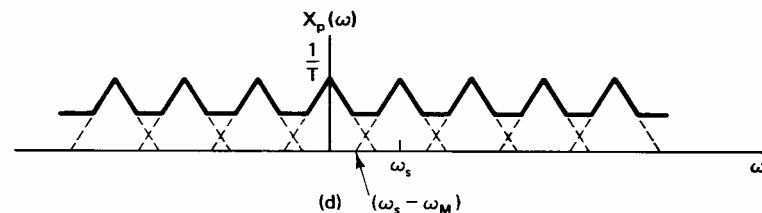
Sampling impulse train



Sampled signal
 $\omega_s > 2\omega_m$



Sampled signal
 $\omega_s < 2\omega_m$
(Aliasing effect)

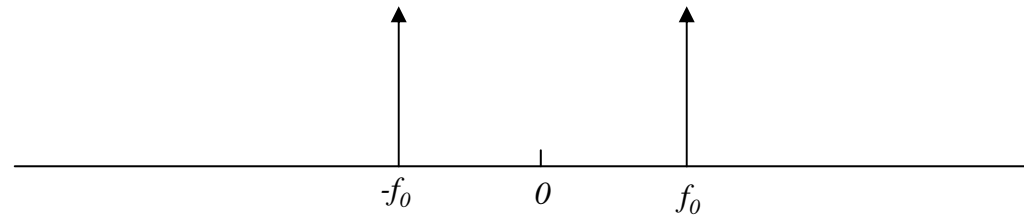


The spectrum of the sampled signal includes the original spectrum and its aliases (copies) shifted to $k f_s$, $k = \pm 1, 2, 3, \dots$. The reconstructed signal from samples has the frequency components upto $f_s/2$.

When $f_s < 2f_m$, aliasing occur.

Sampling of Sinusoid in Frequency Domain

Spectrum of $\cos(2\pi f_0 t)$

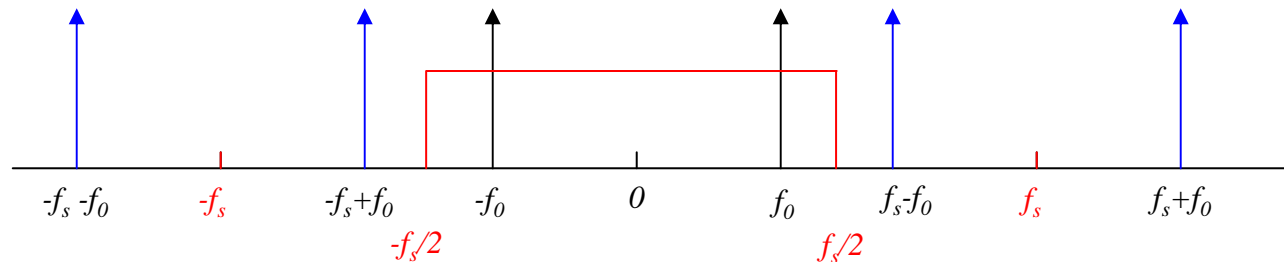


No aliasing

$$f_s > 2f_0$$

$$f_s - f_0 > f_0$$

Reconstructed signal: f_0

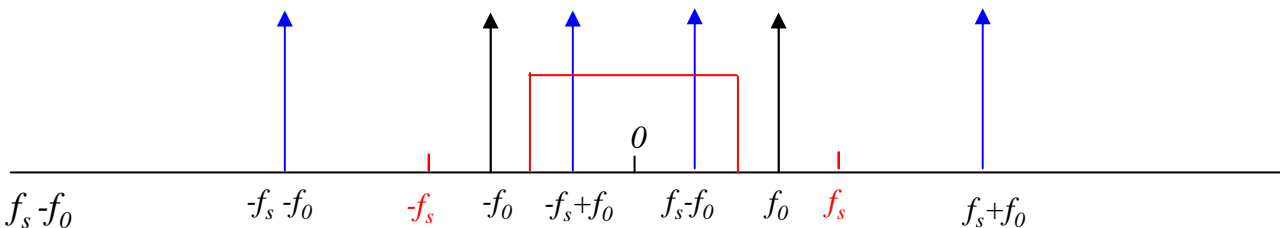


With aliasing

$$f_0 < f_s < 2f_0 \text{ (folding)}$$

$$f_s - f_0 < f_0$$

Reconstructed signal: $f_s - f_0$

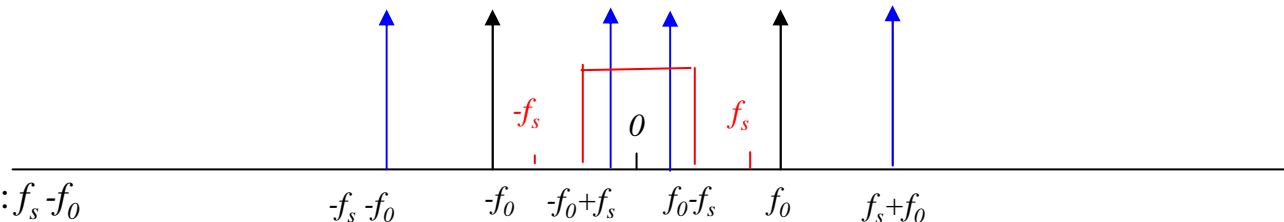


With aliasing

$$f_s < f_0 \text{ (aliasing)}$$

$$f_0 - f_s < f_0$$

Reconstructed signal: $f_s - f_0$



More examples with Sinusoids

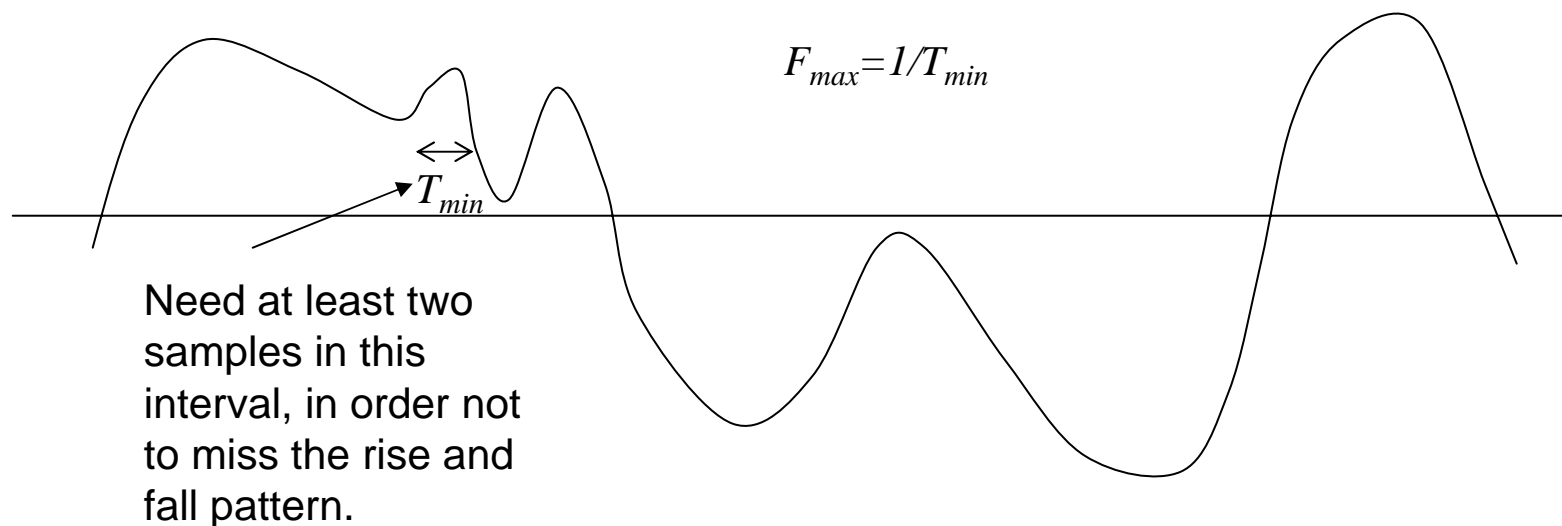
- Demo from DSP First, Chapter 4, aliasing and folding demo
 - Aliasing: $f_s < f_m$ (*perceived frequency: $f_m - f_s$*)
 - Folding: $f_m < f_s < 2f_m$ (*perceived frequency: $f_s - f_m$*)
 - No need to distinguish these two phenomena. Both lead to a false frequency lower than the original frequency

Strobe Movie

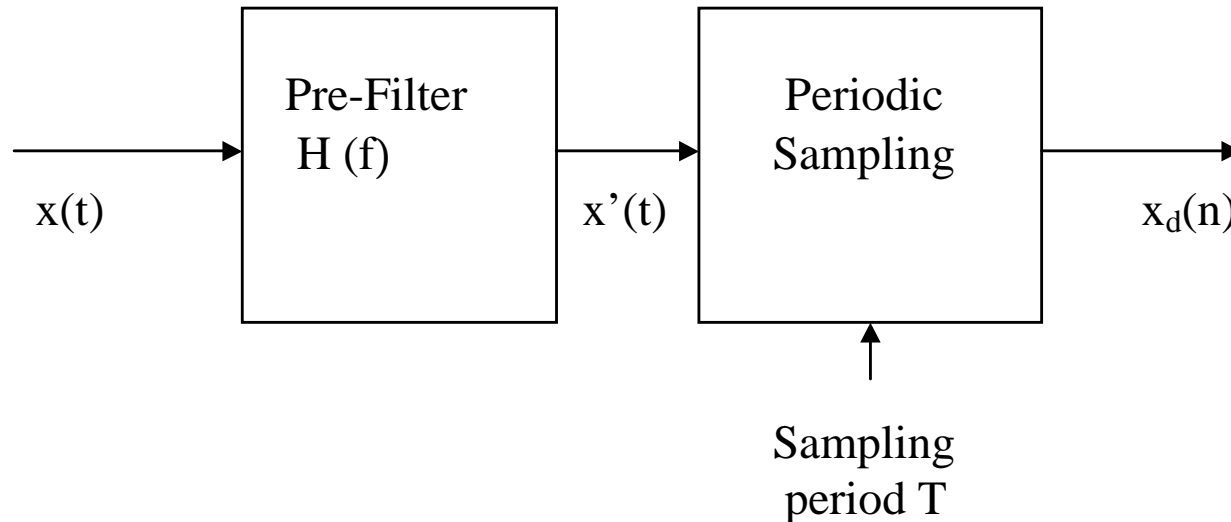
- From DSP First, Chapter 4, Demo on “Strobe Movie”

How to determine the necessary sampling frequency from a signal waveform?

- Given the waveform, find the shortest ripple, there should be at least two samples in the shortest ripple
- The inverse of its length is approximately the highest frequency of the signal



Sampling with Pre-Filtering

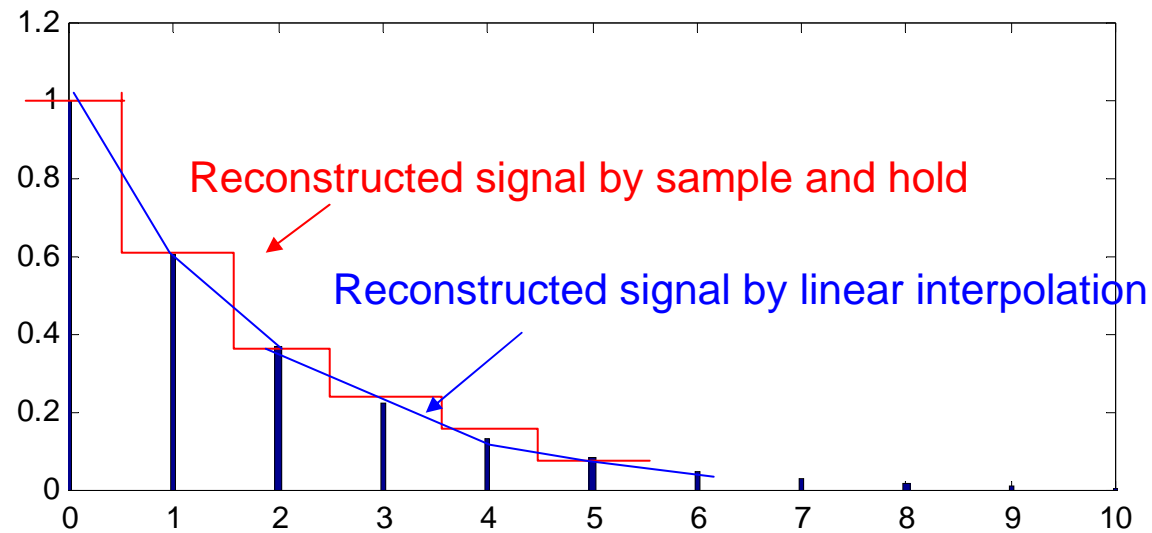


- If $f_s < 2f_m$, aliasing will occur in sampled signal
- To prevent aliasing, pre-filter the continuous signal so that $f_m < f_s/2$
- Ideal filter is a low-pass filter with cutoff frequency at $f_s/2$
(corresponding to sinc functions in time)
- Common practical pre-filter: averaging within one sampling interval

How to Recover Continuous Signals from Samples?

- Connecting samples using interpolation kernels
 - Sampling and hold (rectangular kernels)
 - Linear interpolation (triangular kernels)
 - High order kernels
 - Ideal kernel: sinc function

Sample-and-Hold vs. Linear Interpolation

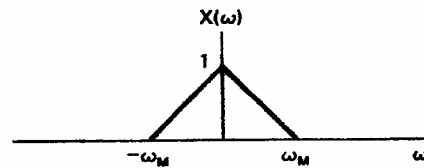


Reconstruction Using Different Kernels

- Demo from DSP First, Chapter 4, demo on “reconstruction”

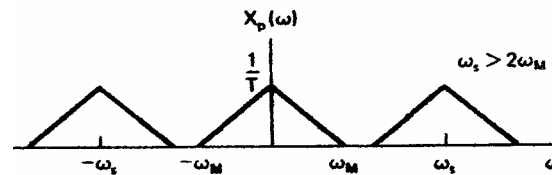
Frequency domain interpretation

Original signal

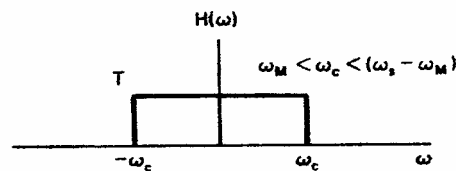


Sampled signal

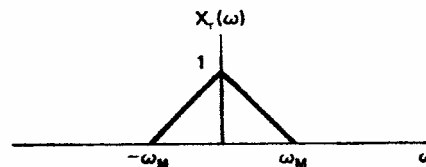
$$\omega_s > 2\omega_M$$



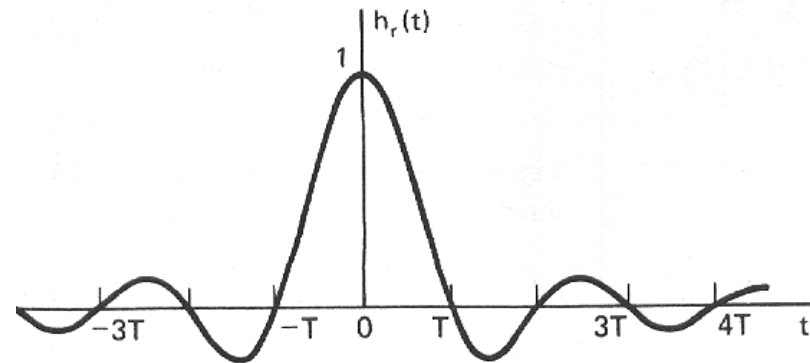
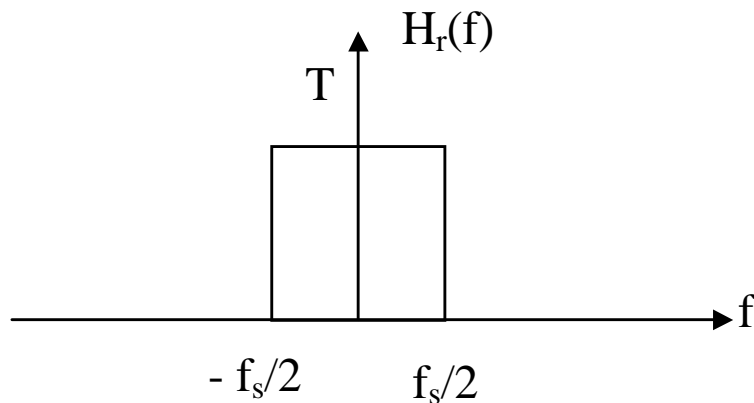
Ideal reconstruction filter
(low-pass)



Reconstructed signal
(=Original signal)



Ideal Interpolation Filter



$$H_r(f) = \begin{cases} T & |f| < f_s/2 \\ 0 & \text{otherwise} \end{cases}$$

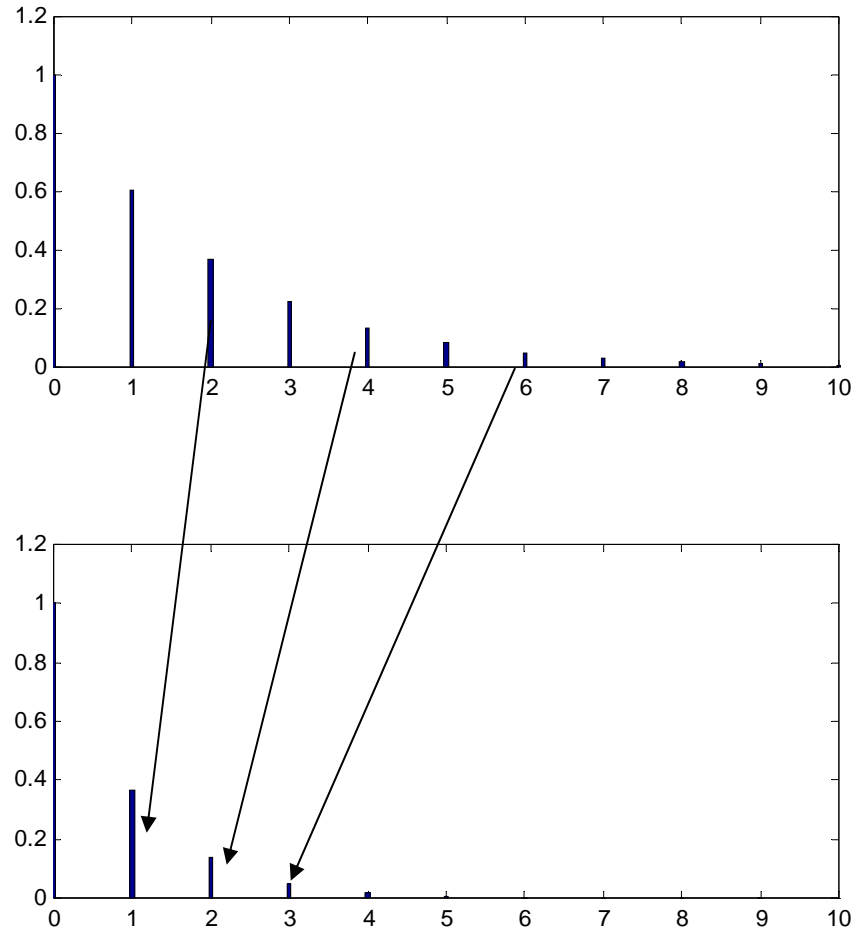
$$h_r(t) = \frac{\sin \pi t / T}{\pi t / T}$$

$$x_r(t) = x_s(t) * h_r(t) = \sum_{n=-\infty}^{\infty} x[n] h_r(t - nT) = \sum_{n=-\infty}^{\infty} x[n] \frac{\sin[\pi(t - nT) / T]}{\pi(t - nT) / T}$$

Sampling Rate Conversion

- Given a digital signal, we may want to change its sampling rate
 - Necessary for image display when original image size differs from the display size
 - Necessary for converting speech/audio/image/video from one format to another
 - Sometimes we reduce sample rate to reduce the data rate
- Down-sampling: reduce the sampling rate
- Up-Sampling: increase the sampling rate

Down-Sampling Illustration

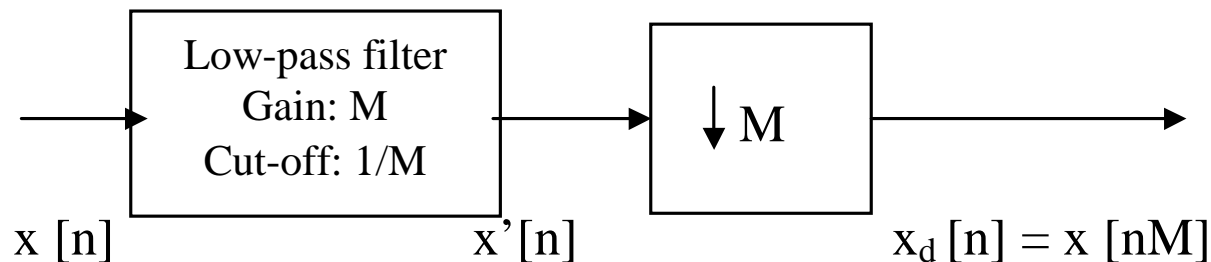


Down-sampling by a factor of 2 = take every other sample

To avoid aliasing of any high frequency content in the original signal, should smooth the original signal before down-sampling -- Prefiltering

Down Sampling by a Factor of M

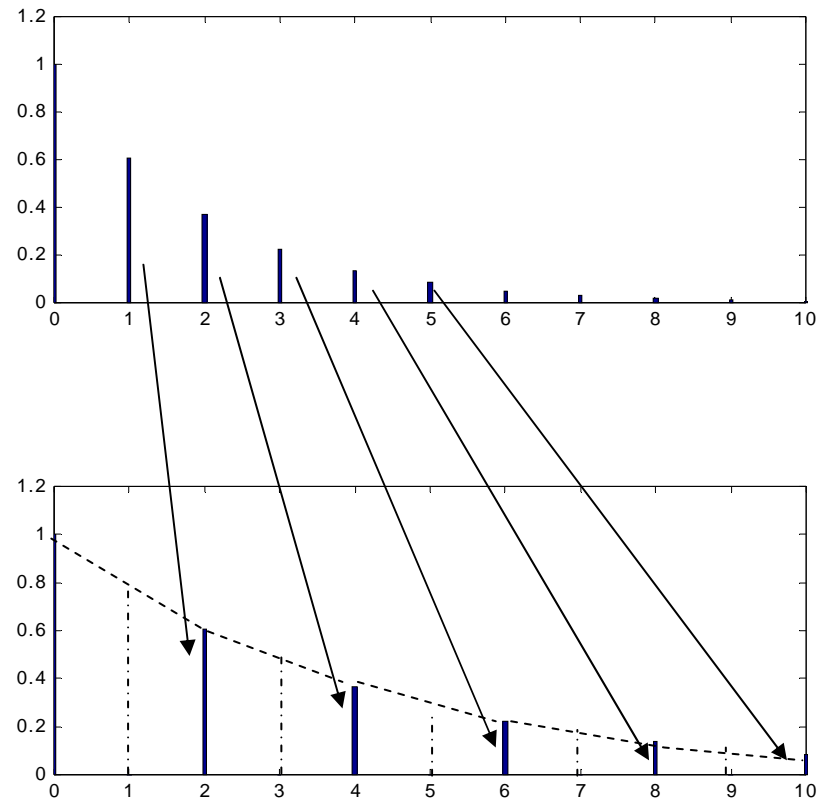
- Take every M -th sample from existing samples
 - $T'=MT, fs'=fs/M$
- Should apply a prefilter to limit the bandwidth of the original signal to $1/M$ -th of the original
- Without prefiltering, aliasing occur in the down-sampled signal.
- Ideal prefilter: low pass filter with cut-off frequency at $1/M$ (maximum digital frequency=1, corresponding to $fs/2$)
- Practical filter: averaging or weighted average over a neighborhood



Down-Sampling Example

- Given a sequence of numbers, down-sample by a factor of 2,
 - Original sequence: 1,3,4,7,8,9,13,15...
 - Without prefiltering, take every other sample:
 - 1,4,8,13,...
 - With 2-sample averaging filter
 - Filtered value= $0.5 \cdot \text{self} + 0.5 \cdot \text{right}$, filter $h[n]=[0.5,0.5]$
 - Resulting sequence:
 - 2, 5.5,8.5,14,...
 - With 3-sample weighted averaging filter
 - Filtered value= $0.5 \cdot \text{self} + 0.25 \cdot \text{left} + 0.25 \cdot \text{right}$, filter $h[n]=[0.25,0.5,0.25]$
 - Resulting sequence (assuming zeros for samples left of first):
 - 1.25, 4.5,8,12.5,...

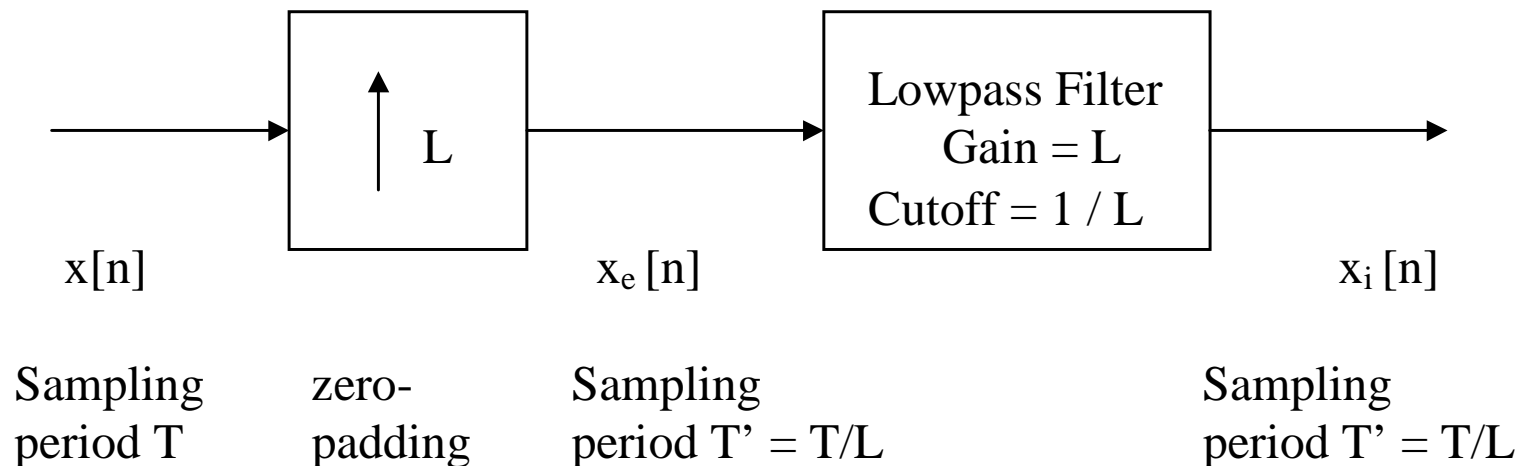
Upsampling by linear interpolation



Missing samples need to be filled from neighboring available samples using interpolation filter

Up Sampling by a Factor of L

- Insert $L-1$ samples between every two existing samples
 - $T'=T/L$, $fs'=fs*L$
 - The estimation of the missing samples from original samples is known as interpolation
- Interpolation can be decomposed into two steps
 - Zero-padding: insert $L-1$ zeros in between every two samples
 - Low-pass filtering: to estimate missing samples from neighbors
 - Simplest interpolation filter: linear interpolation



Up-Sample Example

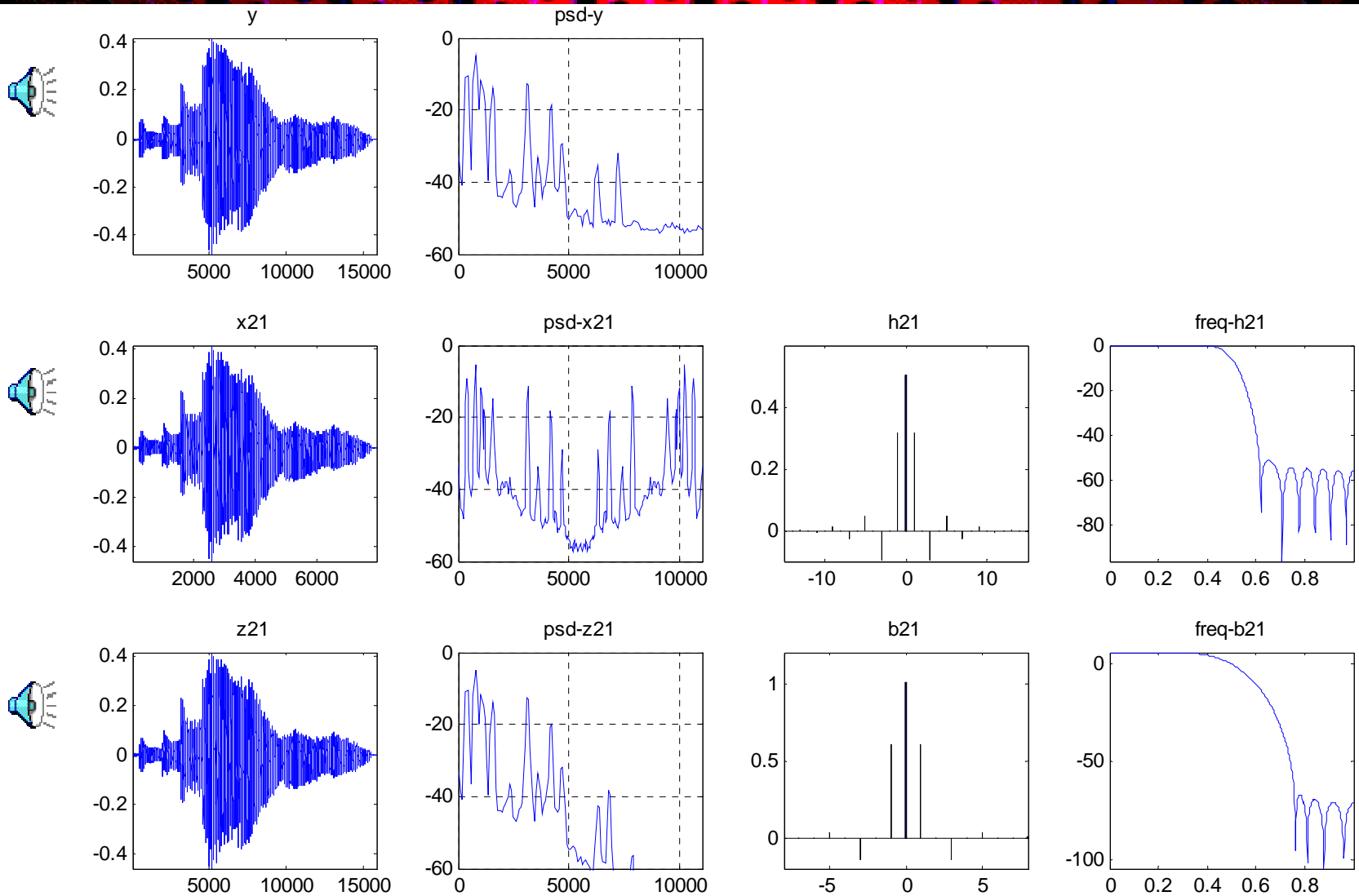
- Given a sequence of numbers, up-sample by a factor of 2
 - Original sequence: 1,3,4,7,8,9,13,15...
 - Zero-padding:
 - 1,0,3,0,4,0,7,0,...
 - Sample and hold
 - Repeat the left neighbor, filter $h[n]=[1,1]$
 - 1,1,3,3,4,4,7,7,...
 - With linear interpolation
 - New sample= $0.5 \times \text{left} + 0.5 \times \text{right}$, filter $h[n]=[0.5,1,0.5]$
 - Resulting sequence:
 - 1,2,3,3.5,4,5.5,7,8,.....

Demonstration

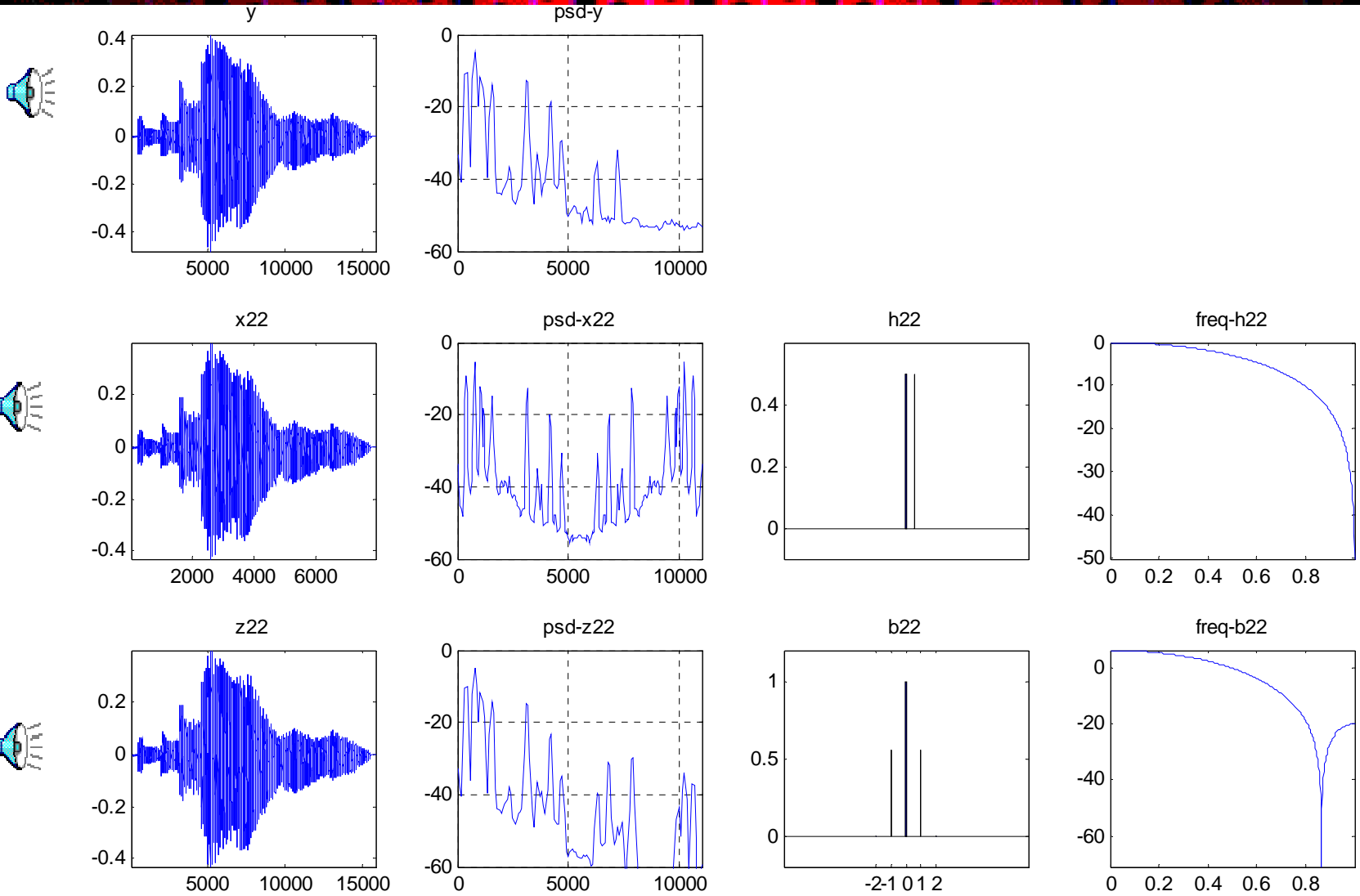
- Demonstrate the effect of down-sampling with different pre-filters, and up-sampling with different interpolation filters
- Compare both sound quality and frequency spectrum
- Matlab code (sampling_demo.m)



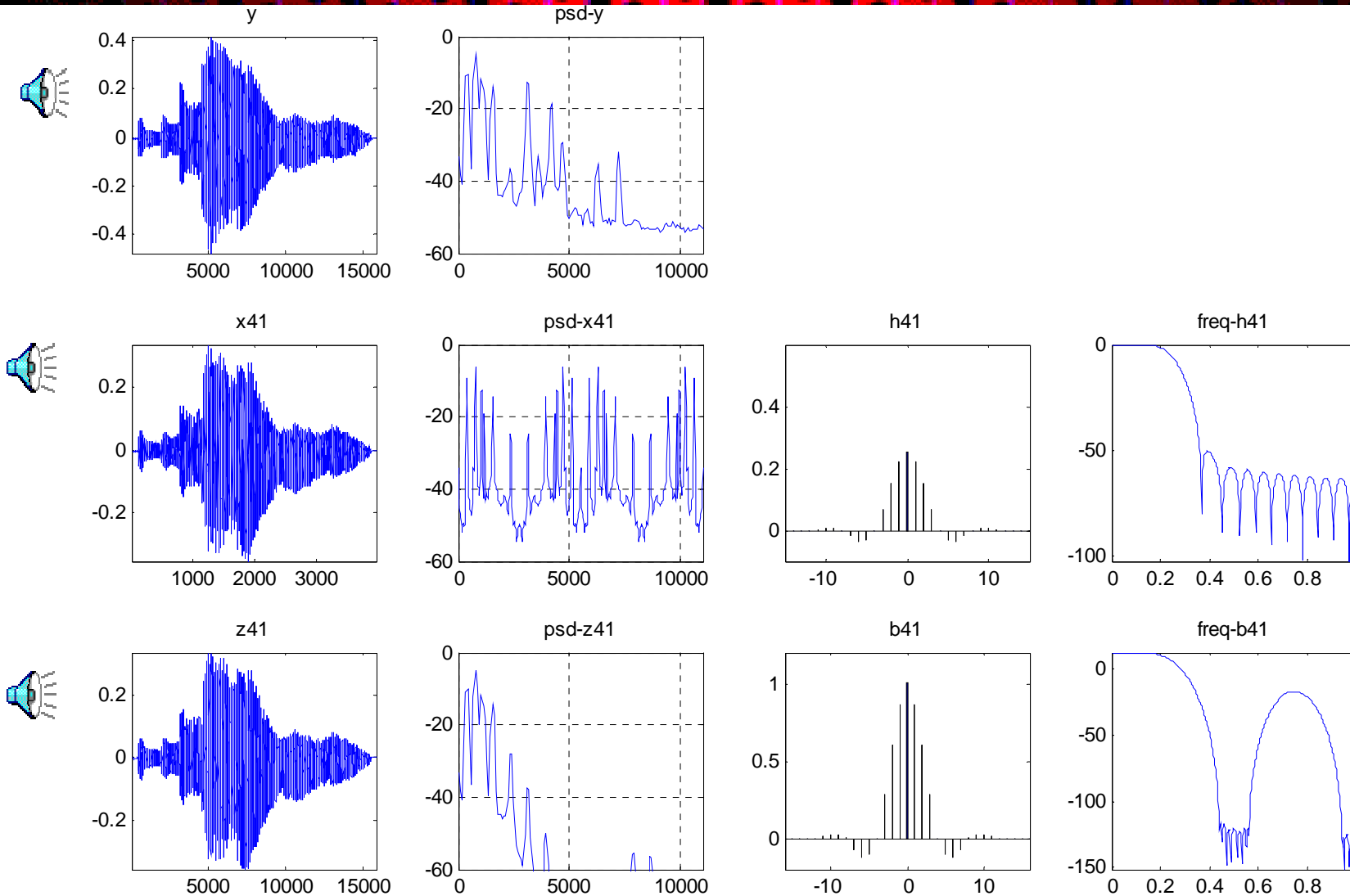
Down-2 followed by up-2, both using good filters



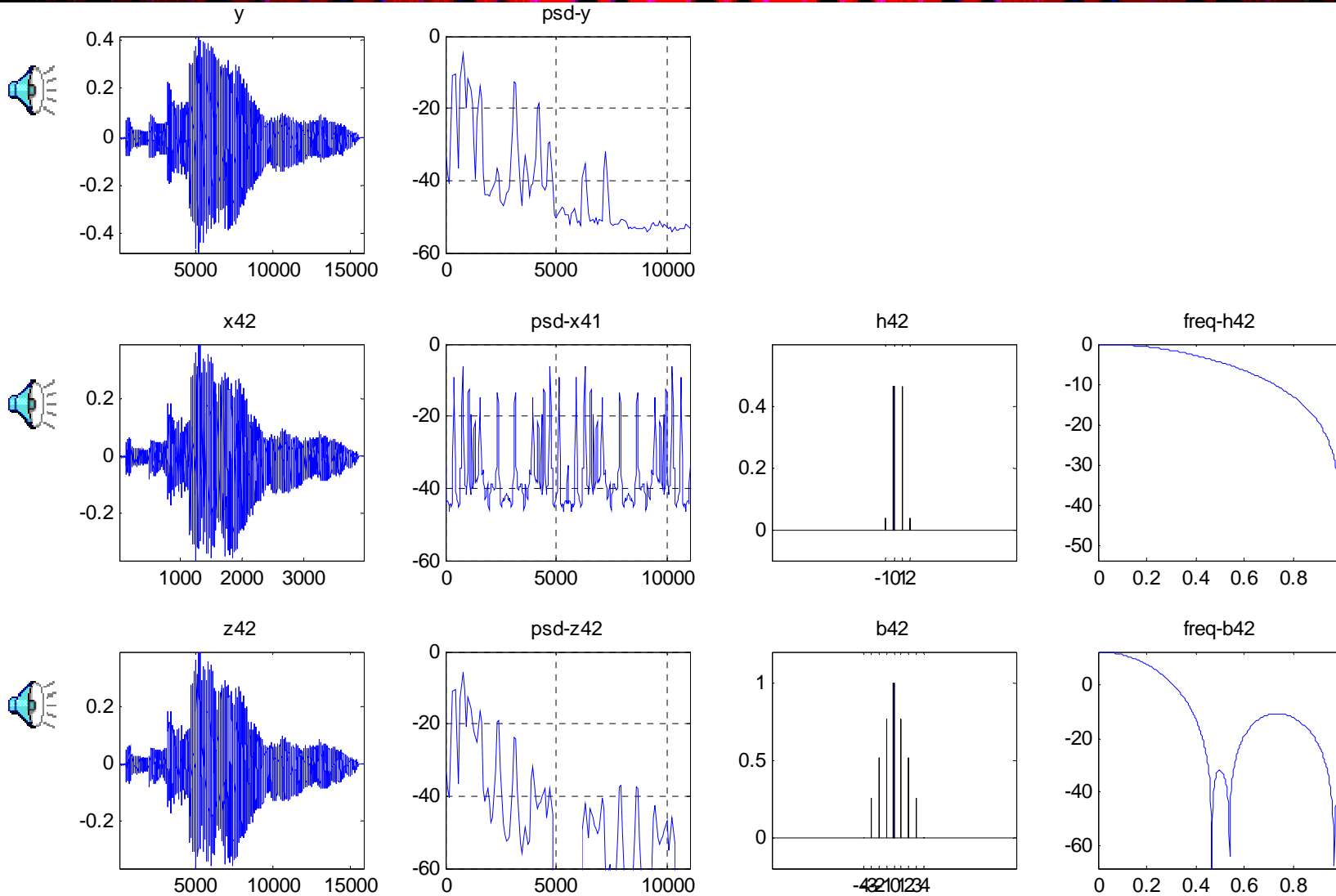
Down-2 followed by up-2, both using bad filters



Down-4 followed by up-4, both using good filters



Down-4 followed by up-4, both using bad filters



MATLAB Code

- Go through the code

What Should You Know (I)

- Sampling:
 - Know the minimally required sampling rate:
 - $f_s > 2 f_{max}$, $T_s < T_{0,min} / 2$
 - Can estimate $T_{0,min}$ from signal waveform
 - Can illustrate samples on a waveform and observe whether the signal is under-sampled.
 - Can plot the spectrum of a sampled signal
 - The sampled signal spectrum contains the original spectrum and its replicas (aliases) at kf_s , $k=\pm 1, 2, \dots$
 - Can determine whether the sampled signal suffers from aliasing
 - Understand why do we need a prefilter when sampling a signal
 - To avoid aliasing
 - Ideally, the filter should be a lowpass filter with cutoff frequency at $f_s / 2$.
 - Can show the aliasing phenomenon when sampling a sinusoid signal using both temporal and frequency domain interpretation

What Should You Know (II)

- Interpolation:
 - Can illustrate sample-and-hold and linear interpolation from samples.
 - Understand why the ideal interpolation filter is a lowpass filter with cutoff frequency at $f_s / 2$.
 - Know the ideal interpolation kernel is the sinc function.
 - Interpolation using the sinc kernel is NOT required
- Sampling Rate Conversion:
 - Know the meaning of down-sampling and upsampling
 - Understand the need for prefiltering before down-sampling
 - To avoid aliasing
 - Know how to apply simple averaging filter for downsampling
 - Can illustrate up-sampling by sample-and-hold and linear interpolation

References

- McClellan, Schafer and Yoder, *DSP First*, Chap. 4
 - Has good conceptual / graphical interpretation (copies provided, Sec. 4.3,4.5 not required)
- Y. Wang, *EL514 Lab Manual*, Exp2: Voice and audio digitization and sampling rate conversion. Sec. 1,2. (copy provided)
- Oppenheim and Willsky, *Signals and Systems*, Chap. 7.
 - Optional reading (More depth in frequency domain interpretation)