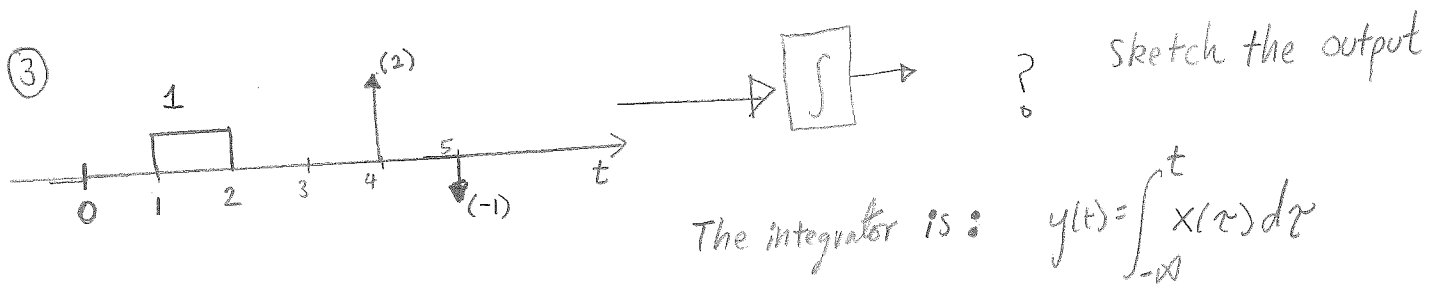


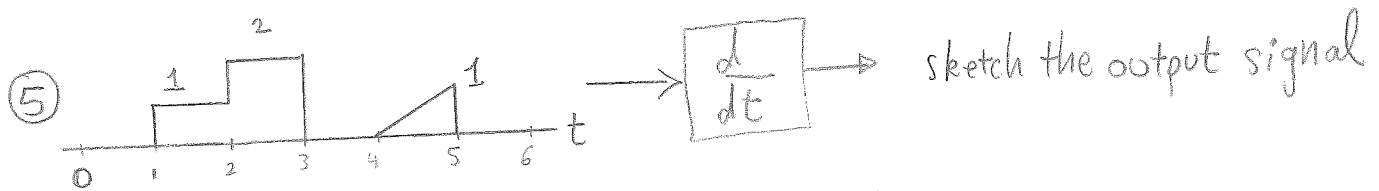
① Given $f(t) = \delta(t) - 2\delta(t-1) + \delta(t-2)$
 $g(t) = t u(t)$
 define $x(t) = f(t) \cdot g(t)$. Accurately sketch $x(t)$.

② An LTI system has impulse response $h(t) = t u(t)$.
 Sketch the output signal produced by input signal
 $x(t) = \delta(t) - 2\delta(t-1) + \delta(t-2)$

③ 

The integrator is: $y(t) = \int_{-\infty}^t x(\tau) d\tau$

④ Same as ③ by system is defined as $y(t) = \int_{t-1}^t x(\tau) d\tau$

⑤ 

⑥ $x(t) = e^t u(-t)$. Sketch the output signal when $x(t)$ is the input to:

(a) integrator $(x(t) \rightarrow \int \rightarrow ?)$

(b) differentiator $(x(t) \rightarrow \frac{d}{dt} \rightarrow ?)$