

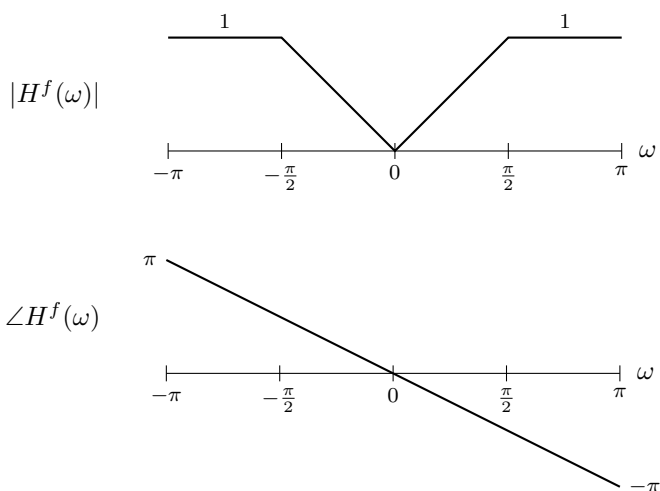
1. A causal LTI system is implemented by the difference equation

$$y(n) = 2x(n) - 0.5y(n-1).$$

- Find the frequency response $H^f(\omega)$ of the system.
- Plot the pole-zero diagram of the system. Based on the pole-zero diagram, roughly sketch the frequency response magnitude $|H^f(\omega)|$.
- Indicate on your sketch of $|H^f(\omega)|$, its exact values at $\omega = 0, 0.5\pi$, and π .
- Find the output signal $y(n)$ produced by the input signal

$$x(n) = 3 + \cos(0.5\pi n).$$

2. A discrete-time LTI system has the frequency response:



- Find the output signal $y(n)$ produced by input signal

$$x(n) = 1 + 2\cos(0.2\pi n + 0.3\pi) + 3(-1)^n.$$

- Is this a real system? Justify your answer.

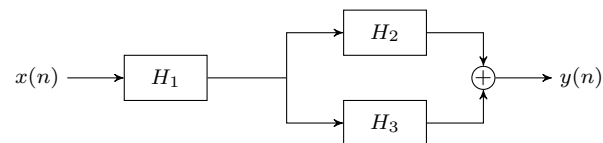
3. The frequency response of a discrete-time LTI system is given by

$$H^f(\omega) = \begin{cases} 0, & 0 \leq |\omega| \leq 0.4\pi \\ -j, & 0.4\pi < \omega < \pi \\ j, & -\pi < \omega < -0.4\pi \end{cases}$$

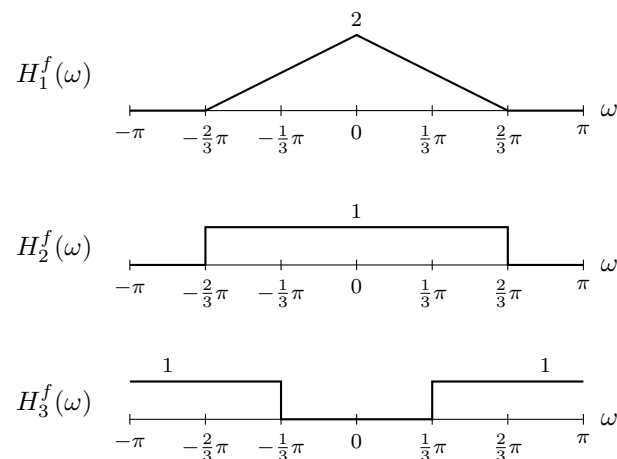
- Sketch the frequency response magnitude $|H^f(\omega)|$ for $|\omega| \leq \pi$.
- Sketch the frequency response phase $\angle H^f(\omega)$ for $|\omega| \leq \pi$.
- Find the output signal $y(n)$ produced by the input signal

$$x(n) = \sin(0.6\pi n).$$

4. Accurately sketch the frequency response of the total system,



where the frequency responses of the LTI subsystems are:



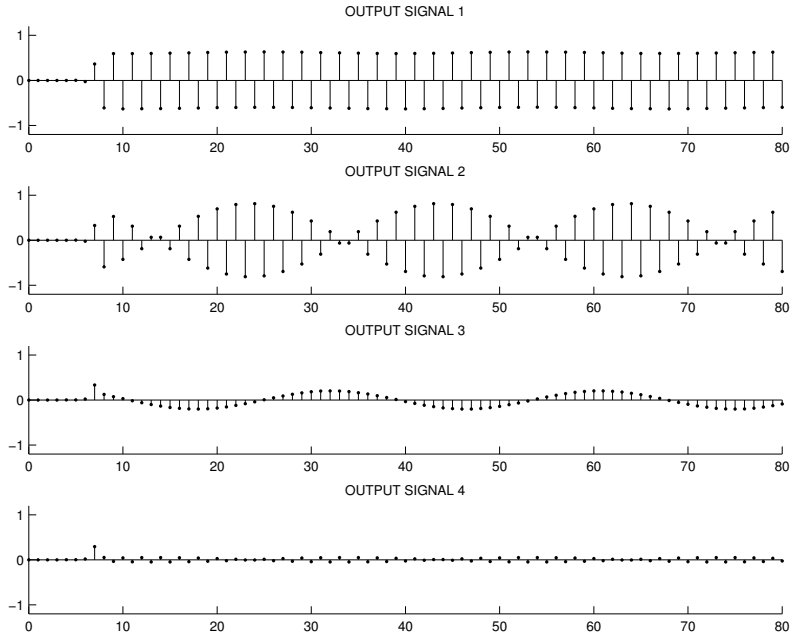
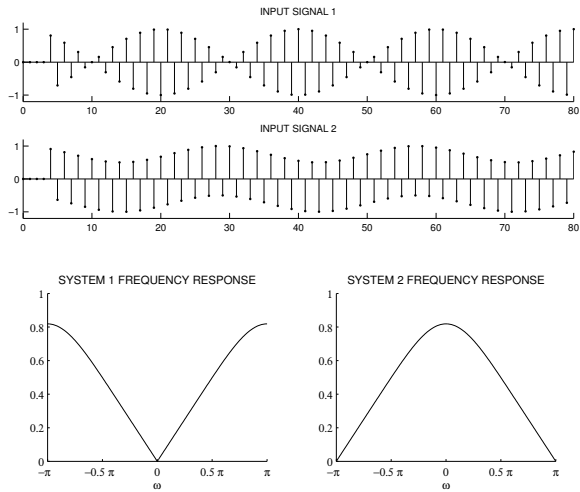
- Matching problem (input / system / output): next page
- Matching problem (pole-zero diagram / frequency response): next page

5.

Each of the two discrete-time signals below are processed with each of two LTI systems. The frequency response magnitude $|H^J(\omega)|$ are shown below. Indicate how each of the four output signals are produced by completing the table below.

Input signal 1 is given by: $\cos(0.95 \pi n) u(n - 4)$

Input signal 2 is given by: $0.25 \cos(0.07 \pi n) u(n - 4) + 0.75 (-1)^n u(n - 4)$



Input signal	System	Output signal
1	1	
1	2	
2	1	
2	2	

6.

Match the pole-zero diagrams with the frequency responses.

