1. Convolution. Sketch the convolution of y(n) = h(n) * x(n)

(a)
$$h(n) = \delta(n-3)$$

 $x(n) = \delta(n) - \delta(n-5)$

(b)
$$h(n) = \delta(n-3) - 2\delta(n-6)$$

 $x(n) = \delta(n) - \delta(n-5)$

(c)
$$h(n) = \delta(n-3) - 2\delta(n-6)$$

 $x(n) = u(n) - u(n-5)$

(d)
$$h(n) = \delta(n) + 2 \,\delta(n-1) + 3 \,\delta(n-2)$$

 $x(n) = \sum_{k=0}^{\infty} \delta(n-4k)$

2. An LTI system has impulse response

$$h(n) = 2\left(\frac{1}{3}\right)^n u(n).$$

Find the system output y(n) produced by the input signal

x(n) = 2.

Note: This input signal starts at 'minus infinity'.

3. Z-transforms. The Z-transform of the signal x(n) is

$$X(z) = 2z^3 + z^{-1} - z^{-2}.$$

- (a) Accurately sketch the signal x(n).
- (b) Define $F(z) = z^{-2} X(z)$. Sketch the signal f(n).
- (c) Define G(z) = X(-z). Sketch the signal g(n).
- (d) Define $H(z) = z^{-2} X(-z)$. Sketch the signal h(n).
- (e) Define $Y(z) = z^{-2} X(1/z)$. Sketch the signal y(n).
- 4. Find the Z-transform X(z) of the signal

$$x(n) = 3\left(\frac{1}{2}\right)^n u(n).$$

Also find and sketch the region of convergence of X(z).

5. Two LTI systems are connected in series

$$x(n) \longrightarrow H_1(z) \longrightarrow H_2(z) \longrightarrow y(n)$$

with transfer functions

$$H_1(z) = 1 + 3 z^{-1} + 4 z^{-2}$$
$$H_2(z) = 2 - z^{-1} + z^{-2}.$$

(a) Find the impulse response h(n) of the total system.

(b) Find output signal y(n) produced by input signal x(n).

